

## ABSTRACT OF THE DISCLOSURE

A steering control unit (3) employs the detected results of environmental conditions given by an environmental-condition detecting unit (5) and issues an operating command to a steering motor ( $M_1$ ) attached to a steering mechanism (1) as a steering actuator when, for example, an object approaching from behind at a speed exceeding a predetermined speed is detected and when the steering control unit (3) decides there is the possibility that the object may collide with one's own vehicle. Then the steering control unit (3) causes the steering motor ( $M_1$ ) to make the steering mechanism (1) perform forcible steering in order to avoid danger.